

# Gauge Invariances in Non-Commutative Theories

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# Non-Commutativity

- Arises in perturbative string theory.
- Dynamics of D-branes in a constant background magnetic field can be described by a non-commutative gauge theory.
  
- First introduced by *H S Snyder* to regulate short-distance singularities in Quantum field theory
- This structure in spacetime introduces a lower bound in the continuity of space-time.
  
- ...
- ...

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# In this talk

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- We look at some classical aspects (origins) of Non-commutative theories
- Are there any classical systems, which when quantised can give rise to non-commutativity in co-ordinates?
- If such systems exist, what can you do with them?
- Existence of such systems are indicated by Lagrangians

# Some Literature

- 1 Lagrangians can be written down.
- 2 They indicate the corresponding theories are constrained systems.
- 3 One earlier paper  $\longrightarrow$  R Jackiw  
*“Physical Instances of Non-Commuting Co-ordinates ”*  
NP B (Proc. Suppl.) 108 (2002) 30-36
- 4 A A Deriglazov  
*“Non-commutative Version of an Arbitrary Nondegenerated Mechanics ”*  
hep-th 0208072 (2002)
- 5 Very recent paper  $\longrightarrow$  F S Benfica & H O Girotti  
*“Non-commutative Quantum Mechanics as a Gauge Theory ”*  
PR D 798 (2009) 125024

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# Our Work

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- 1 We look at two Lagrangians (one already considered in above paper)
  - 2 Non-Commutativity of co-ordinates will be reproduced in different ways.
  - 3 Using Dirac brackets.
  - 4 Equivalent gauge theories are generated.
  - 5 The Moyal product also naturally arises in these gauge theories.

# What is non-commutativity?

Suppose  $x^i$ ,  $i = 1, 2, \dots$  are the co-ordinates for a system.

Then non-commutativity  $\implies$  the commutator

$$[\hat{x}^i, \hat{x}^j] = i\theta^{ij}$$

where  $\theta^{ij}$  is an antisymmetric constant matrix.

Continuity of corresponding space breaks down. An uncertainty relation is induced,

$$\Delta x^i \Delta x^j \geq i\theta_{ij}$$

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In the space defined by such non-commuting co-ordinates, functions do not obey the usual product rule

$$(fg)(x) \neq f(x)g(x)$$

The relevant product is the Moyal product

$$(f * g)(x) = e^{i\theta^{ij}\partial_i^1\partial_j^2} f(x_1)g(x_2)|_{x_1=x_2}$$

# 1<sup>st</sup> Lagrangian : Equations of Motion & Phase Space

Consider the Lagrangian in first order form,

$$\mathbb{L} = v_i \dot{q}^i - h_0(q^i, v_j) + \dot{v}_i \theta^{ij} v_j \quad i, j = 1, \dots, N$$

- First given by A A Deriglazov

- $q^i, v_j$  are configuration space variables
- Equations of Motion

$$\dot{q}^i = 2\theta^{ij} \dot{v}_j + \frac{\partial h_0}{\partial v_i} \quad \text{and} \quad \dot{v}_i = -\frac{\partial h_0}{\partial q^i}$$

- The canonical momenta

$$p_i = \frac{\partial \mathbb{L}}{\partial \dot{q}^i} = v_i \quad \text{and} \quad \pi^i = \frac{\partial \mathbb{L}}{\partial \dot{v}_i} = \theta^{ij} v_j$$

- No velocities, so constraints arise

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# Constraints & the Hamiltonian

- $\phi_i = (p_i - v_i) \approx 0$  and  $\psi^i = \pi^i - \theta^{ij} v_j \approx 0$
- These define a surface  $\Sigma_{2N}$  in phase space
- These are second class constraints  $\implies$

$$\{\phi_i, \phi_j\} = 0, \quad \{\phi_i, \psi^j\} = -\delta_i^j, \quad \{\psi^i, \psi^j\} = -2\theta^{ij}$$

- Canonical Hamiltonian

$$H_0 = h_0 + (p_i - v_i)\dot{q}^i + (\pi^i - \theta^{ij} v_j)\dot{v}_i$$

- Total Hamiltonian

$$H_T = h_0 + \left( \frac{\partial h_0}{\partial v_i} - 2\theta^{ij} \frac{\partial h_0}{\partial q^i} \right) \phi_i - \frac{\partial h_0}{\partial q^i} \psi^i$$

- Hamiltonian equations of motion same as Lagrange equations.

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# Dirac Brackets

- Defined whenever 2<sup>nd</sup> class constraints are present

- $$\{A, B\}_{DB} = \{A, B\} - \{A, \Phi_\alpha\} C_{\alpha\beta}^{-1} \{\Phi_\beta, B\}$$

where  $\Phi_\alpha \equiv (\phi_i, \psi^i)$  and  $C_{\alpha\beta} = \{\Phi_\alpha, \Phi_\beta\}$

Here  $C = \begin{pmatrix} 0 & -\mathbb{I} \\ \mathbb{I} & -2\theta \end{pmatrix}$  and  $C^{-1} = \begin{pmatrix} -2\theta & \mathbb{I} \\ -\mathbb{I} & 0 \end{pmatrix}$

- $$\{q^i, q^j\}_{DB} = -2\theta^{ij}$$
$$\{q^i, v_j\}_{DB} = \delta^i_j, \{q^i, p_j\}_{DB} = -2\theta^i_j, \{q^i, \pi^j\}_{DB} = -\theta^{ij}$$
- Transition to Quantum Mechanics  $\implies [\hat{q}^i, \hat{q}^j] = -2i\theta^{ij}$
- First given by A A Deriglazov
- Truly independent variables —  $(q^i, p_i)$

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# Equivalent Gauge Theory

- Original System has no gauge invariance  $\implies$  no 1<sup>st</sup> class constraints
- Can introduce gauge invariance here, and can reproduce non-commutativity in a different way
- Look at  $\{\phi_i, \phi_j\} = 0, \{\phi_i, \psi^j\} = -\delta_i^j, \{\psi^i, \psi^j\} = -2\theta^{ij}$
- The  $\phi_i$  form a *first class* constraint subset.
- The  $\psi^i$  form a *gauge-fixing-like* constraint subset.
- Redefine  $\phi_i$  as  $\chi_i = (\{\phi, \psi\}^{-1})_i^j \phi_j = -\phi_i,$
- **Discard** (no longer consider) the  $\psi^j$  as constraints.
- We have a new (smaller) constraint surface  $\sum_{\mathbb{N}},$  defined by only  $\chi_i \approx 0.$

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# Gauge Invariant Hamiltonian & Other Variables

- On this  $\sum_N$ ,  $H_T$  no longer ensures time-independence of  $\chi_i$ .
- $H_T$  must be *modified* to  $\tilde{H}_T$ , such that  $\{\chi_i, \tilde{H}_T\} = 0$
- We get  $\tilde{H}_T = e^{-\psi^j \partial_{q^j}} h_0$ . where  $\partial_{q^j} = \frac{\partial}{\partial q^j}$
- Other gauge invariant variables are  $\tilde{A} =: e^{-\psi^j \hat{\chi}_j} : \mathbb{A}$   
 $\Rightarrow \tilde{q}^j = q^j - \psi^j; \quad \tilde{v}_i = v_i; \quad \tilde{p}_i = p_i; \quad \tilde{\pi}^i = \pi^i - \psi^i$
- All these have zero Poisson brackets with the  $\chi_i$
- Equivalent gauge theory given by the  $\chi_i \approx 0$  and  $\tilde{H}_T$
- Gauge transformations are generated by the  $\chi_i$

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# Non-commutative co-ordinates once again

- The Poisson brackets between the gauge invariant quantities

$$\{\tilde{q}^i, \tilde{q}^j\} = -2\theta^{ij}; \quad \{\tilde{q}^i, \tilde{p}_j\} = \delta^i_j; \quad \{\tilde{q}^i, \tilde{\pi}^j\} = -\theta^{ij}$$

- On quantising, the gauge-invariant  $\tilde{q}^i$  go over to **non-commuting** operators!!
- The space of gauge invariant co-ordinates is the same as that of non-commuting co-ordinates.
- Similar results obtained by *Benfica and Girotti*, using **extension of phase space**.
- Here **no extension of phase space**.  
All results are in the **original phase space**

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# The Moyal Product

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- The ordinary product of two functions in non-commuting space can be rewritten as a *Moyal Product*.
- For two functions  $A, B$  the gauge invariant functions  $\tilde{A}, \tilde{B}$  are given by

$$\tilde{A}(q^i, v_j) = e^{-\psi^i \partial_{q_i}} A = A(\tilde{q}^i, \tilde{v}_i); \quad \tilde{B}(q^i, v_j) = e^{-\psi^i \partial_{q_i}} B = B(\tilde{q}^i, \tilde{v}_i)$$

- Then  $\tilde{A}(q^i, v_j) \tilde{B}(q^i, v_j) = \text{Moyal product}$   
 $= (A * B)(\tilde{q}^i, \tilde{v}_j)$

# Proof of Moyal Product

## Proof.

The quantities  $\tilde{A}(q^i, v_j)$  &  $\tilde{B}(q^i, v_j)$  can be redefined upto terms in the first class constraints  $\chi_i$ .

$$\tilde{A}(q, v) = e^{-\psi^i \partial_{q_i} - \chi_i \partial_{v_i}} A; \quad \tilde{B}(q, v) = e^{-\psi^i \partial_{q_i} - \chi_i \partial_{v_i}} B;$$

The Fourier transforms of  $\tilde{A}(q, v)$  &  $\tilde{B}(q, v)$  are

$$\begin{aligned} \tilde{A}(q^i, v_j) &= \frac{1}{(2\pi)^N} \int d^N m d^N n e^{-(\psi^i \partial_{q_i} + \chi_i \partial_{v_i})} e^{i(m_j q^j + n^j v_j)} A(m, n) \\ &= \frac{1}{(2\pi)^N} \int d^N m d^N n e^{-(\psi^i m_i + \chi_i n^i)} e^{i(m_i q^i + n^i v_i)} A(m, n) \\ \tilde{B}(q^i, v_j) &= \frac{1}{(2\pi)^N} \int d^N m d^N n e^{-(\psi^i r_i + \chi_i s^i)} e^{i(r_i q^i + s^i v_i)} A(m, n) \end{aligned}$$



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## proof continued

Taking the product  $\tilde{A}(q^i, v_j)\tilde{B}(q^i, v_j)$ , the product on its RHS can be modified using Baker-Campbell-Hausdorff formula

$$\begin{aligned} e^X e^Y &= e^{X+Y} e^{-\frac{1}{2}\{X,Y\}} e^{\frac{1}{6}(2\{Y,\{X,Y\}\} + \{X,\{X,Y\}\})} \dots \\ X &= -i(\psi^i m_i + \chi_i n^i); \quad Y = -i(\psi^i r_i + \chi_i s^i) \end{aligned}$$

Using  $\{X, Y\} = -[2\theta^{ij} m_i r_j - m_i s^i + n^i r_i]$ ,  $\{Y, \{X, Y\}\} = \{X, \{X, Y\}\} = 0$ , we get,

$$\begin{aligned} &= \frac{1}{(2\pi)^{2N}} \int d^N m d^N n d^N r d^N s e^{i[(m_i + r_i)\tilde{q}^i + (n^i + s^i)\tilde{v}_i]} \\ &\quad e^{\frac{1}{2}[2\theta^{ij} m_i r_j - m_i s^i + n^i r_i]} A(m, n) B(r, s) \end{aligned}$$

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## proof continued

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which is the same as the Fourier transform of the usual Moyal product:

$$(\mathbb{A} * \mathbb{B})(\tilde{q}^i, \tilde{v}_j) = e^{\frac{i}{2}(-2\theta^{ij})\partial_{q^i}\partial_{q'^j}} e^{\frac{i}{2}(0)\partial_{v_i}\partial_{v'_j}} e^{\frac{i}{2}(\delta^i_j)\partial_{q^i}\partial_{v'_j}} e^{\frac{i}{2}(-\delta^i_j)\partial_{v_i}\partial_{q'^j}}$$

in which the  $\tilde{q}^i$  are usual non-commuting co-ordinates.

Thus the ordinary product of two gauge invariant functions can be rewritten as the Moyal products of the corresponding two non-invariant functions of non-commuting co-ordinates.

## 2<sup>nd</sup> Lagrangian : Equations of Motion & Phase Space

- Using  $q^i$  alone as the  $N$  co-ordinates, consider

$$\mathbb{L} = \dot{q}^i (\theta^{-1})_{ij} \dot{q}^j - h_0(q^i), \quad i, j = 1, 2, \dots, N$$

where  $(\theta^{-1})$  is the inverse of the original  $\theta$

- Lagrange equations of motion  $\longrightarrow \dot{q}^i = -\frac{1}{2} \theta^{ij} \frac{\partial h_0}{\partial \dot{q}^j}$
- The canonical momenta are  $p_i = \frac{\partial \mathbb{L}}{\partial \dot{q}^i} = (\theta^{-1})_{ij} \dot{q}^j$   
span a  $2N$ -dimensional phase space
- Fundamental PBs —  $\{q^i, q^j\} = 0$ ;  $\{q^i, p_j\} = \delta^i_j$
- No velocities again; so constraints appear

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# Constraints & the Hamiltonian

- There are  $N$  constraints –  $\phi'_i = p_i - (\theta^{-1})_{ij} q^j \approx 0$  defining an  $N$ -dimensional surface  $\Sigma'_N$ .

- Second class constraints –  $C_{ij} = \{\phi'_i, \phi'_j\} = -2(\theta^{-1})_{ij}$

- Canonical Hamiltonian is

$$H_0(q, p) = h_0 + \sum_{i,j} [p_i - (\theta^{-1})_{ij} q^j] \dot{q}^i$$

- Total Hamiltonian is  $H_T = h_0 - \frac{1}{2} \sum_{i,j} \phi'_i \theta^{ij} \frac{\partial h_0}{\partial q^j}$

- Hamilton's equations of motion

$$\dot{q}^i = \{q^i, H_T\} = -\frac{1}{2} \theta^{ij} \frac{\partial h_0}{\partial q^j}; \quad \dot{p}_i = -\frac{1}{2} \frac{\partial h_0}{\partial q^i}$$

on the surface  $\Sigma'_N$ .

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# Dirac Brackets

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- Here  $\{A, B\}_{DB} = \{A, B\} - \{A, \phi'_i\}(C^{-1})^{ij}\{\phi'_j, B\}$

where  $C^{-1}$  is the matrix  $-\frac{1}{2}\theta$

- Applying this we get  $\{q^i, q^j\}_{DB} = -\frac{1}{2}\theta^{ij}$  and

$$\{q^i, p_j\}_{DB} = \frac{1}{2}\delta^i_j, \quad \{p_i, p_j\}_{DB} = \frac{1}{2}(\theta^{-1})_{ij}$$

- Again upon quantisation, these Dirac brackets go over to commutators, and we get **non-commutative** co-ordinates.

Note: There is no gauge invariance here

# Equivalent Gauge Theory for the Second System

- Once again, we can introduce gauge invariance here.
- Note – The number of constraints here is less than in the earlier case.
- Gauge invariance can be induced by either enlarging the phase space, or by remaining with this phase space ( $2N$ -dimensional).
- We work in the same phase space.
- However, must now split the  $N$  constraints  $\phi'_i$  into two subsets, at least one of which obeys the *first class* property. The other subset must behave a gauge-fixing subset.
- As it is, a general (constant) matrix  $\theta$  doesn't permit this splitting.

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# The classification of constraints

- Classification in the above sense is thus **non-trivial**.
- No problem at all for just **two** constraints. Either one is taken as first class, the other gauge-fixing like.
- A single classification throughout is needed.
- May be possible here since  $\theta$  is a constant matrix.
- Consider a matrix  $S$  such that  $S^T \theta^{-1} S = (\theta')^{-1}$ , where  $(\theta')^{-1}$  is of the form  $(\theta')^{-1} = \begin{pmatrix} 0 & E \\ -E & 0 \end{pmatrix}$
- The submatrix  $E$  is of dimension  $\frac{N}{2} \times \frac{N}{2}$ .
- The same matrix  $S$  can be used to transform the constraint set  $\phi'$  as  $\phi' \longrightarrow \phi'' = S^T \phi'$

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## Classification of constraints contd.

- For the constraints  $\phi'_i$ , since formally  $\{\phi', \phi'\} = -2\theta^{-1}$  the above two transformations can be used to get

$$\begin{aligned}\{\phi'', \phi''\} &= \{S^T \phi', \phi' S\} = S^T \{\phi', \phi'\} S \\ &= -2 (S^T \theta^{-1} S) = -2(\theta')^{-1}\end{aligned}$$

- The form of the matrix  $(\theta')^{-1}$  implies that the modified constraints  $\phi''$  can now be divided into two subsets,

$$\phi''_\alpha = \chi'_\alpha; \quad \phi''_{\alpha + \frac{N}{2}} = \psi'_\alpha \quad (\alpha = 1, 2, \dots, \frac{N}{2})$$

- Classification is obvious if we look at the PBs,

$$\{\chi'_\alpha, \chi'_\beta\} = 0; \quad \{\chi'_\alpha, \psi'_\beta\} = -2E_{\alpha\beta}; \quad \{\psi'_\alpha, \psi'_\beta\} = 0$$

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## Choice of the first class subset

- Can choose either the  $\chi'$  or the  $\psi'$  as the first class subset, and the remaining as gauge-fixing-like subset.
- Redefine the  $\chi'$  as  $\chi''_{\alpha} = -\frac{1}{2} (E)_{\alpha\beta}^{-1} \chi'_{\beta}$  &  $\psi''_{\alpha} = \psi'_{\alpha}$ .
- Retain  $\chi''_{\alpha}$  as first class constraint subset and discard the  $\psi''_{\alpha}$ .
- The constraint surface, defined by only  $\chi''_{\alpha} \approx 0$ , is  $\sum_{\alpha=1}^N$
- However, on this  $\sum_{\alpha=1}^N$ ,  $H_T$  is **not invariant** under transformations generated by the  $\chi''_{\alpha}$ !

$$\{\chi''_{\alpha}, H_T\} \neq 0.$$

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# Gauge Invariant Hamiltonian

- In terms of the  $\chi'_\alpha, \psi'_\alpha$  rewrite the  $H_T$  as

$$\begin{aligned} H_T &= h_0 + \sum_{ij} u^i \phi'_j = h_0 + \sum_{ij} u^i \phi''_j \\ &= \frac{1}{2} \sum_{i,\alpha} \left[ \chi'_\alpha (E^{-1})^{\alpha\beta} (S^T)_{\beta+\frac{N}{2}}^i - \psi'_\alpha (E^{-1})^{\alpha\beta} (S^T)_\beta^i \right] \frac{\partial h_0}{\partial q^i} \end{aligned}$$

where the various transformations (above) are used.

- Formally the gauge invariant Hamiltonian is

$$\tilde{H}_T =: e^{-\psi'' \hat{\chi}''} : H_T, \quad [ : \hat{\chi}'' : \equiv \{ \chi'', () \} ] \quad \chi''_\alpha = ((E))_{\alpha\beta}^{-1} \chi'_\beta$$

- The gauge invariant Hamiltonian is

$$\tilde{H}_T = e^{-\frac{1}{2} (E^{-1} S^T)^{\alpha i} \psi''_\alpha \frac{\partial}{\partial q^i}} h_0$$

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# Gauge Invariant variables & Non-Commutativity

- For a general function  $A$ , the gauge invariant

counterpart is  $\tilde{A} = e^{-\frac{1}{2}(\mathbf{E}^{-1}\mathbf{S}^T)^{\alpha i} \psi''_{\alpha} \frac{\partial}{\partial q^i}} A$

- Then  $\tilde{q}^i = q^i - \frac{1}{2} (\mathbf{E}^{-1}\mathbf{S}^T)^{\alpha i} \psi''_{\alpha}$ , and

$$\tilde{p}_i = p_i + \frac{1}{2} (\mathbf{E}^{-1}\mathbf{S}^T)^{\alpha j} \psi''_{\alpha} (\theta^{-1})_{ji}$$

- The  $\tilde{q}^i$  have **non-zero** Poisson brackets  $\implies$  upon quantisation, they are **non-commuting!**

$$\{\tilde{q}^i, \tilde{q}^j\} = -\frac{1}{2}\theta^{ij}; \quad \{\tilde{q}^i, \tilde{p}_j\} = \frac{1}{2}\delta^i_j; \quad \{\tilde{p}_i, \tilde{p}_j\} = \frac{1}{2}(\theta^{-1})_{ij}$$

- Thus, the space of gauge-invariant co-ordinates is **non-commuting.**

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# Gauge Invariance and The Moyal Product

- Here also, product of two gauge invariant functions can be rewritten as the Moyal product.

- Use the  $1^{\text{st}}$  class  $\chi''_i$  to write, for any  $A(q^i)$ ,

$$\tilde{A} = e^{-\frac{1}{2}(\mathbb{E}^{-1}S^T)^{\alpha i} \psi''_{\alpha} \frac{\partial}{\partial q^i} - \frac{1}{2}(S)^i \alpha + \frac{N}{2} \chi''_{\alpha} \frac{\partial}{\partial q^i}} A,$$

with a similar expression for any other  $B(q^i)$ .

- Take Fourier transforms for  $\tilde{A}, \tilde{B}$ , and take their product.
- Use Baker-Campbell-Hausdorff appropriately.

$$\begin{aligned} \tilde{\tilde{A}}\tilde{\tilde{B}} &= \frac{1}{(2\pi)^N} \int d^N m d^N n e^{i(m_i+n_i)\tilde{q}^i} e^{-\frac{1}{2}\theta^{ij}m_i n_j} A(m_i)B(n_i) \\ &= \frac{1}{(2\pi)^N} \int d^N m d^N n e^{-\frac{1}{2}\theta^{ij} \frac{\partial}{\partial \tilde{q}^i} \frac{\partial}{\partial \tilde{q}^j}} e^{im_i \tilde{q}^i} e^{in_i \tilde{q}^i} A(m_i)B(n_i) \\ &= (\tilde{A} * \tilde{B})(\tilde{q}) \end{aligned}$$

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- Classical aspects of Non-Commutative Theories.
- What are the classical theories that can generate non-commutativity of co-ordinates upon quantisation?
- Two theories, given by two Lagrangians.
- Both are theories involving second class constraints.
- In both cases, **Dirac brackets** were used and **non-commutative co-ordinates** were generated.
- Equivalent gauge theories were constructed.
- **Gauge invariant** co-ordinates are **non-commuting** upon quantisation.
- In the space spanned by such gauge invariant co-ordinates, ordinary product of functions are the same as the Moyal product.

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